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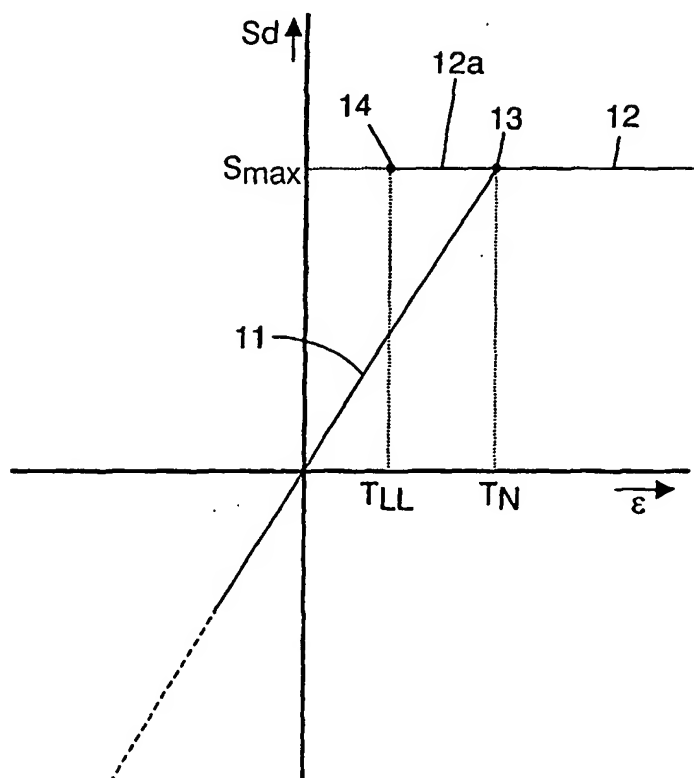
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[Continued on next page]

(54) Title: CONTROLLER DEVICE WITH SWITCHABLE CHARACTERISTIC



(57) **Abstract:** A controller (30) is capable of operating in two possible operative modes, each mode having a corresponding characteristic (11; 12). Said characteristics have an overlap in a range of error signal values [TLL-TN]. The controller is capable of switching from one mode to another, based on the value of the time-derivative ( $\dot{e}$ ) of the input error signal ( $e$ ), so that, for a certain input error signal within said range [TLL-TN], the controller can be in any of its modes.

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